

PHASE - NEUTRAL BACK EMF, ENCODER ABSOLUTE POSITION

U-NEUTRAL

V-NEUTRAL

W-NEUTRAL

2. Motor poles:	38
3. Operating Speed, max:	1500 RPM
4. Base speed (max speed at peak torque), Ref, at 440 VAC RMS operating voltage:	725 RPM
5. Continuous stall torque, max, at max winding temperature in a 40C ambient:	49.2 Nm (435 lb-in)
6. Winding temperature, max, in a 40C ambient:	150 degrees C
7. Continuous stall current, max:	19.1 Amps 0 to peak
8. Heatsink size, aluminum, attached to front mounting flange for continuous torque specifications:	407 x 407 x 19.1mm (16 x 16 x 0.75 inch)
9. Peak stall torque, max:	110 Nm (974 lb-in)
10. Peak stall current, max:	58.7 Amps 0 to peak
11. Rated Speed (UL file and motor nameplate Rated RPM):	1000 RPM
12. Continuous power rating, max:	3.03 KVV (4.07 HP)
13. Speed at continuous power rating:	
14. Continuous torque, max, at continuous power rating.	30.7 Nill (272 10-11)
15. Continuous current, Ref, at continuous power rating:	12.4 Amps 0 to peak
16. Operating voltage, Ref (Not for direct connection to AC line):	400 VAC KIVIS
17. Insulation class:	155C (Class F)
18. Housing temperature, max:	125C (257F)
19. Ke, +/-10%, phase to phase at 25C +/- 5C:	342 V/KRPIVI U to peak
20. Kt (sine), Ref, at 25C +/- 5C:	2.83 Nm/Amp (25.05 lb-in/Amp) 0 to peak
21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:	0.73 01113
22. Winding inductance, Ref, phase to phase:	6.9 mH
23. Dielectric rating of motor power connections (U,V,W), to ground for 1 second:	2352 VAC RMS 50/60 Hz
24. Audible noise, Ref, at 1 meter distance:	65 dbA
25. Rotor inertia, +/- 10%:	0.028 kg-m² (0.25 lb-in-sec²)
26. Friction torque, Ref:	1.4 NM (12.4 ID-IN)
27. Cogging torque, Ref:	0.79 Nm (7.0 lb-ln) peak to peak
28. Thermal resistance, Ref, winding to ambient:	0.302 degrees C/watt
29. Thermal time constant, Ref, winding to ambient:	76 minutes
30. Product weight, Ref:	28.6 kg (63 lb)
31. Shipping weight, Ref:	36.8 kg (81 lb)
32. Operating ambient temperature:	0C to 40C (32F to 104F)
33. Storage ambient temperature:	-30C to 70C (-22F to 158F)

Speed, torque and current specifications are for operation with Allen Bradley drives.

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Ge	eneral Specifications, continued:	
34	Relative humidity, non-condensing:	5% to 95%
35	. Liquid / dust protection:	IP65
36	. Shock, max, 6 msec duration:	20 g peak
37	. Vibration, max, 30 to 2000 Hz:	2.5 g peak
38	. Bearing arrangement: None internal to motor. Shaft is supported by customer's shaft / bearing system.	
39	Shaft material:	Steel
40	Paint color, gloss level, except rear cover:	Black, 20 to 35 gloss units
41	Rear cover color (Pantone color code), painted or exposed material color:	Cool gray # 5, 0 to 20 gloss units

42. Shaft, key (if provided), front mounting surface, and connectors are not painted.

## Feedback Specifications:

. Feedback interface type (encoder supplier proprietary), order designation:	Endat, 2.2/01
2. SIN, COS waveform output signals/rev:	2048 sinusoids/rev
<ol><li>SIN, COS waveform amplitude, measured differentially from SIN+ to SIN-, or COS+ to COS-:</li></ol>	0.75 to 1.2 VAC peak to peak
I. SIN, COS voltage offset with respect to ECOM, +/- 0.5 VDC:	2.5 VDC
<ol> <li>DATA+, DATA-, CLK+, CLK- signals applicable standard, signals type:</li> </ol>	RS 485, Synchronous
<ol> <li>CLK+, CLK- clock frequency, Ref, when operating with Kinetix Endat adapter kit:</li> </ol>	468.75 kHz
. Communication hierarchy: Encoder is slave, communication is externally initiated.	
3. Single turn absolute position value range:	0 to 8191 (13 bit)
Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
0. Memory storage capacity available for Rockwell parameters, EEPROM, min:	64 words, 16 bits/word
1. EPWR 5V (encoder power) input voltage:	3.6 to 14 VDC
2. EPWR 5V continuous input current,max, at 5.0 VDC:	TBD mADC
3. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:	TBD ADC
4. TS+, TS- PTC Thermistor transition temperature, +/-5C:	160 degrees C
5. TS+, TS- PTC thermistor circuit resistance, Ref, at thermistor transition temperature:	1100 ohms
6. TS+, TS- PTC thermistor circuit resistance, Ref, at 25 C +/- 5C:	160 ohms
7. TS+, TS- PTC thermistor resistance vs temperature curves applicable standards:	DIN 44081 / 44082
8. TS+, TS- PTC thermistor circuit configuration (number of thermistors):	2 in series

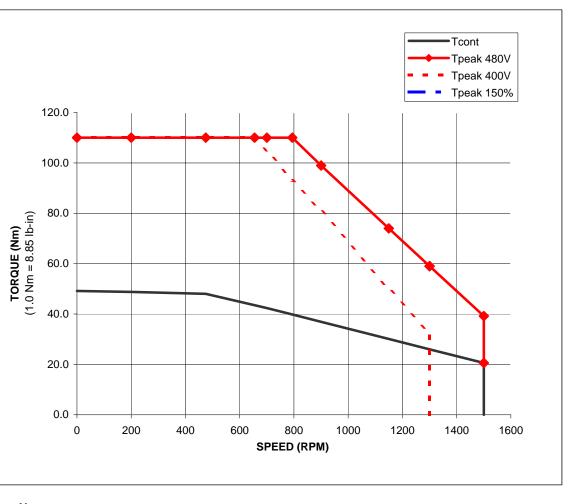
## Notes:

1. "Ref" denotes untoleranced specifications, provided for reference only.

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## RDB-B29019-3B72AA Performance with 2094-BC07-M05S at 480 and 400 VAC 3 phase Converter Input, 40C Motor Ambient

		TOR	QUE	
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V	Tpeak 150%
	Nm	Nm	Nm	Nm
0	49.2	110	110	#N/A
200	48.8	110	110	#N/A
475	48	110	110	#N/A
655	43.5	110	110	#N/A
700	42.4	110	105	#N/A
794	39.8	110	93	#N/A
900	36.9	99	81	#N/A
1150	30.1	74	50	#N/A
1300	26	59	32.4	#N/A
1300	26	59	0	#N/A
			#N/A	#N/A
1500	20.6	39.2	#IN/A	#IN/A
1500 1500	20.6 0	39.2 20.6	#N/A #N/A	#N/A #N/A
		20.6	#N/A	-
		20.6	-	
1500 SPEED		20.6	#N/A	-
1500	0	20.6 TOR	#N/A QUE	#N/A
1500 SPEED	0 Tcont	20.6 TOR Tpeak 480V	#N/A QUE Tpeak 400V	#N/A Tpeak 150%
1500 SPEED RPM	0 Tcont Ib-in	20.6 TOR Tpeak 480V Ib-in	#N/A QUE Tpeak 400V Ib-in	#N/A Tpeak 150% Ib-in
1500 SPEED RPM 0	0 Tcont Ib-in 435	20.6 TOR Tpeak 480V Ib-in 974	#N/A QUE Tpeak 400V Ib-in 974	#N/A Tpeak 150% Ib-in #N/A
1500 SPEED RPM 0 200	0 Tcont Ib-in 435 432	20.6 TOR Tpeak 480V Ib-in 974 974	#N/A QUE Tpeak 400V Ib-in 974 974	#N/A Tpeak 150% Ib-in #N/A #N/A
1500 SPEED RPM 0 200 475	0 Tcont Ib-in 435 432 425	20.6 TOR Tpeak 480V Ib-in 974 974 974	#N/A QUE Tpeak 400V Ib-in 974 974 974	#N/A Tpeak 150% Ib-in #N/A #N/A #N/A
1500 SPEED RPM 0 200 475 655	0 Tcont Ib-in 435 432 425 385	20.6 TOR Tpeak 480V Ib-in 974 974 974 974	#N/A QUE Tpeak 400V Ib-in 974 974 974 974	#N/A Tpeak 150% Ib-in #N/A #N/A #N/A #N/A
1500 SPEED RPM 0 200 475 655 700	0 Tcont Ib-in 435 432 425 385 375	20.6 TOR Tpeak 480V Ib-in 974 974 974 974 974 974	#N/A QUE Tpeak 400V Ib-in 974 974 974 974 974 929	#N/A Tpeak 150% Ib-in #N/A #N/A #N/A #N/A #N/A
1500 SPEED RPM 0 200 475 655 700 794	0 Tcont Ib-in 435 432 425 385 375 352	20.6 TOR Tpeak 480V Ib-in 974 974 974 974 974 974 974	#N/A QUE Tpeak 400V Ib-in 974 974 974 974 929 823	#N/A Tpeak 150% Ib-in #N/A #N/A #N/A #N/A #N/A #N/A
1500 SPEED RPM 0 200 475 655 700 794 900	0 Tcont lb-in 435 432 425 385 375 352 327	20.6 TOR Tpeak 480V Ib-in 974 974 974 974 974 974 974 876	#N/A QUE Tpeak 400V Ib-in 974 974 974 974 974 929 823 717	#N/A Tpeak 150% Ib-in #N/A #N/A #N/A #N/A #N/A #N/A #N/A
1500 SPEED RPM 0 200 475 655 700 794 900 1150	0 Tcont lb-in 435 432 425 385 375 352 327 266	20.6 TOR Tpeak 480V Ib-in 974 974 974 974 974 974 974 876 655	#N/A QUE Tpeak 400V Ib-in 974 974 974 974 974 974 929 823 717 443	#N/A Tpeak 150% Ib-in #N/A #N/A #N/A #N/A #N/A #N/A #N/A #N/A
1500 SPEED RPM 0 200 475 655 700 794 900 1150 1300	0 Tcont lb-in 435 432 425 385 375 352 327 266 230	20.6 TOR Tpeak 480V Ib-in 974 974 974 974 974 974 974 974 974 974	#N/A QUE Tpeak 400V Ib-in 974 974 974 974 974 929 823 717 443 287	#N/A Tpeak 150% Ib-in #N/A #N/A #N/A #N/A #N/A #N/A #N/A #N/A



## Notes:

1. Nm torque values shown are converted from tested lb-in data.

2. "Tpeak 150%" line shown applies when the drive peak current limit is set to 150% of the drive continuous current rating.

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