

PHASE - NEUTRAL BACK EMF, ENCODER ABSOLUTE POSITION

U-NEUTRAL

V-NEUTRAL

W-NEUTRAL

General Specifications:	
1. Motor type: 3 phase, wye winding, permanent magnet rotor, totally enclosed, non-ventilated.	
2 Motor poloci	38
3. Operating Speed, max:	
4. Base speed (max speed at peak torque), Ref, at 440 VAC RMS operating voltage:	98 Nm (867 lb-in)
5. Continuous stall torque, max, at max winding temperature in a 40C ambient:	
6. Winding temperature, max, in a 40C ambient:	150 degrees C
7. Continuous stall current, max:	10.7 Amps 0 to peak
8. Heatsink size, aluminum, attached to front mounting flange for continuous torque specifications:	407 x 407 x 19.1mm (16 x 16 x 0.75 inch)
9. Peak stall torque, max:	
10. Peak stall current, max:	33.0 Amps 0 to peak
11. Rated Speed (UL file and motor nameplate Rated RPM):	400 RPM
12. Continuous power rating, max:	3.33 KVV (4.47 NP)
13. Speed at continuous power rating.	413 NFW
15. Continuous current, Ref, at continuous power rating:	8.4 Amps 0 to peak
16. Operating voltage, Ref (Not for direct connection to AC line):	480 VAC RIMS
17. Insulation class:	155C (Class F)
18. Housing temperature, max:	125C (257F)
19. Ke, +/-10%, phase to phase at 25C +/- 5C:	1233 V/kRPM 0 to peak
20. KU(SINE), KEI, al 200 +/- 00.	10.20 Nill/Allp (90.20 ID-II/Allp) 0 to peak
21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:	3.48 ohms
22. Winding inductance, Ref, phase to phase:	
23. Dielectric rating of motor power connections (U,V,W), to ground for 1 second:	
24. Audible noise, Ref, at 1 meter distance:	
25. Rotor inertia, +/- 10%:	
20. Fristen territe Dat	2.7  Mm (22.0  lb in)
27. Consistent formula Defi	1 59 Nm (11 0 lb in) nock to nock
<ul> <li>27. Cogging forque, Ref.</li> <li>28. Thermal resistance, Ref. winding to ambient:</li> <li>20. Thermal time constant. Def. winding to ambient:</li> </ul>	
29. Thermal time constant, Ref, winding to ambient:	86 minutes
29. Thermal time constant, ref, winding to ambient.	42.7 kg (94 lb)
30. Product weight, Ref:	50.8 kg (112 lb)
31. Shipping weight, Ref:	0C to 40C (32F to 104F)
32. Operating ambient temperature:	
33. Storage ambient temperature:	-300 10 / 00 (-227 10 1307)
NT - 4	
Notes:	
1. "Ref" denotes untoleranced specifications, provided for reference only.	
2. Speed, torque and current specifications are for operation with Allen Bradley drives.	trical Shoot 2 of 4

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Rockwell Automation		RDB-B2902	24-3B7	72AA	Size		1000006	10000065579	Ver	
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Ge	eneral Specifications, continued:	
34	Relative humidity, non-condensing:	5% to 95%
35	. Liquid / dust protection:	IP65
36	. Shock, max, 6 msec duration:	20 g peak
37	. Vibration, max, 30 to 2000 Hz:	2.5 g peak
38	. Bearing arrangement: None internal to motor. Shaft is supported by customer's shaft / bearing system.	
39	Shaft material:	Steel
40	Paint color, gloss level, except rear cover:	Black, 20 to 35 gloss units
41	Rear cover color (Pantone color code), painted or exposed material color:	Cool gray # 5, 0 to 20 gloss units

42. Shaft, key (if provided), front mounting surface, and connectors are not painted.

## Feedback Specifications:

. Feedback interface type (encoder supplier proprietary), order designation:	Endat, 2.2/01
2. SIN, COS waveform output signals/rev:	2048 sinusoids/rev
<ol><li>SIN, COS waveform amplitude, measured differentially from SIN+ to SIN-, or COS+ to COS-:</li></ol>	0.75 to 1.2 VAC peak to peak
I. SIN, COS voltage offset with respect to ECOM, +/- 0.5 VDC:	2.5 VDC
<ol> <li>DATA+, DATA-, CLK+, CLK- signals applicable standard, signals type:</li> </ol>	RS 485, Synchronous
<ol> <li>CLK+, CLK- clock frequency, Ref, when operating with Kinetix Endat adapter kit:</li> </ol>	468.75 kHz
. Communication hierarchy: Encoder is slave, communication is externally initiated.	
3. Single turn absolute position value range:	0 to 8191 (13 bit)
Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.	
0. Memory storage capacity available for Rockwell parameters, EEPROM, min:	64 words, 16 bits/word
1. EPWR 5V (encoder power) input voltage:	3.6 to 14 VDC
2. EPWR 5V continuous input current,max, at 5.0 VDC:	TBD mADC
3. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive:	TBD ADC
4. TS+, TS- PTC Thermistor transition temperature, +/-5C:	160 degrees C
5. TS+, TS- PTC thermistor circuit resistance, Ref, at thermistor transition temperature:	1100 ohms
6. TS+, TS- PTC thermistor circuit resistance, Ref, at 25 C +/- 5C:	160 ohms
7. TS+, TS- PTC thermistor resistance vs temperature curves applicable standards:	DIN 44081 / 44082
8. TS+, TS- PTC thermistor circuit configuration (number of thermistors):	2 in series

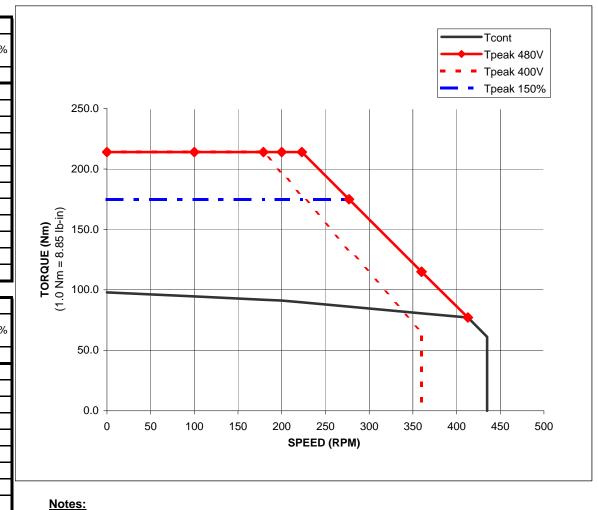
## Notes:

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## RDB-B29024-3B72AA Performance with 2094-BC02-M02S at 480 and 400 VAC 3 phase Converter Input, 40C Motor Ambient

TORQUE									
		TOR	QUE						
SPEED RPM	Tcont	Tpeak 480V	Tpeak 400V	Tpeak 150%					
	Nm	Nm	Nm	Nm					
0	98	214	214	175					
100	94.6	214	214	175					
179	91.9	214	214	175					
200	91.2	214	197	175					
223	89.7	214	178	175					
277	86.1	175	133	175					
360	80.6	115	65.6	#N/A					
360	80.6	115	0	#N/A					
413	77.1	77.1	#N/A	#N/A					
435	61.2	#N/A	#N/A	#N/A					
435	0	#N/A	#N/A	#N/A					
#N/A	#N/A	#N/A	#N/A	#N/A					
#N/A	#N/A			#N/A					
#N/A	#N/A		#N/A QUE	#N/A					
SPEED	#N/A			#N/A Tpeak 150%					
		TOR	QUE						
SPEED	Tcont	TOR Tpeak 480V	QUE Tpeak 400V	Tpeak 150%					
SPEED RPM	Tcont Ib-in	TOR Tpeak 480V Ib-in	QUE Tpeak 400V Ib-in	Tpeak 150% Ib-in					
SPEED RPM 0	Tcont Ib-in 867	TOR Tpeak 480V Ib-in 1894	QUE Tpeak 400V Ib-in 1894	Tpeak 150% Ib-in 1549					
SPEED RPM 0 100	Tcont Ib-in 867 837	TOR Tpeak 480V Ib-in 1894 1894	QUE Tpeak 400V Ib-in 1894 1894	Tpeak 150% Ib-in 1549 1549					
SPEED RPM 0 100 179	Tcont Ib-in 867 837 813	TOR Tpeak 480V Ib-in 1894 1894 1894	QUE Tpeak 400V Ib-in 1894 1894 1894	Tpeak 150% Ib-in 1549 1549 1549					
SPEED RPM 0 100 179 200	Tcont Ib-in 867 837 813 807	TOR Tpeak 480V Ib-in 1894 1894 1894 1894	QUE Tpeak 400V Ib-in 1894 1894 1894 1744	Tpeak 150% Ib-in 1549 1549 1549 1549					
SPEED RPM 0 100 179 200 223	Tcont Ib-in 867 837 813 807 794	TOR Tpeak 480V Ib-in 1894 1894 1894 1894 1894	QUE Tpeak 400V Ib-in 1894 1894 1894 1744 1575	Tpeak 150% Ib-in 1549 1549 1549 1549 1549					
SPEED RPM 0 100 179 200 223 277	Tcont Ib-in 867 837 813 807 794 762	TOR Tpeak 480V Ib-in 1894 1894 1894 1894 1894 1894 1549	QUE Tpeak 400V Ib-in 1894 1894 1894 1744 1575 1177	Tpeak 150% Ib-in 1549 1549 1549 1549 1549 1549 1549					
SPEED RPM 0 100 179 200 223 277 360	Tcont Ib-in 867 837 813 807 794 762 713	TOR Tpeak 480V Ib-in 1894 1894 1894 1894 1894 1894 1549 1018	QUE Tpeak 400V Ib-in 1894 1894 1894 1744 1575 1177 581	Tpeak 150% Ib-in 1549 1549 1549 1549 1549 1549 1549 #N/A					
SPEED RPM 0 100 179 200 223 277 360 360	Tcont Ib-in 867 837 813 807 794 762 713 713	TOR Tpeak 480V Ib-in 1894 1894 1894 1894 1894 1894 1549 1018 1018	QUE Tpeak 400V Ib-in 1894 1894 1894 1744 1575 1177 581 0	Tpeak 150% Ib-in 1549 1549 1549 1549 1549 1549 #N/A #N/A					
SPEED RPM 0 100 179 200 223 277 360 360 360 413	Tcont Ib-in 867 837 813 807 794 762 713 713 682	TOR Tpeak 480V Ib-in 1894 1894 1894 1894 1894 1894 1549 1018 1018 682	QUE Tpeak 400V Ib-in 1894 1894 1894 1744 1575 1177 581 0 #N/A	Tpeak 150% Ib-in 1549 1549 1549 1549 1549 1549 #N/A #N/A #N/A					



1. Nm torque values shown are converted from tested lb-in data.

2. "Tpeak 150%" line shown applies when the drive peak current limit is set to 150% of the drive continuous current rating.

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