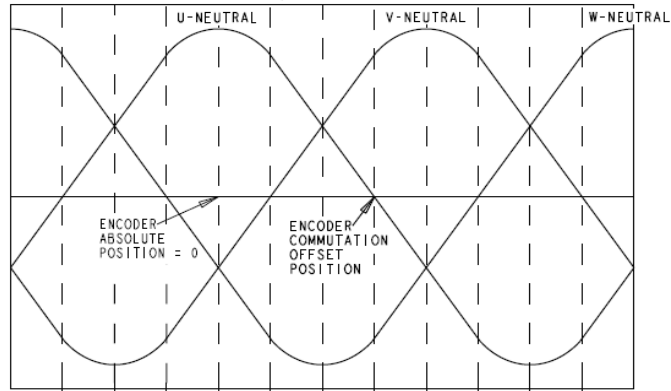
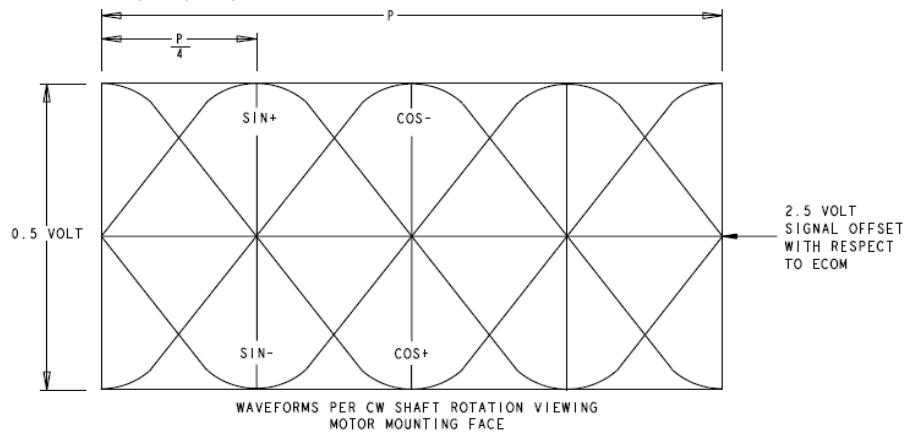


PHASE - NEUTRAL BACK EMF, ENCODER ABSOLUTE POSITION



-30° 0° 30° 60° 90° 120° 150° 180° 210° 240° 270° 300° 330° ELECTRICAL DEGREES

SIN+, SIN-, COS+, COS- ENCODER OUTPUT WAVEFORMS




NOTES:

General Specifications:

1. Motor type: 3 phase, wye winding, permanent magnet rotor, totally enclosed, non-ventilated.	
2. Motor poles:	46
3. Operating Speed, max:	600 RPM
4. Base speed (max speed at peak torque), Ref, at 440 VAC RMS operating voltage:	351 RPM
5. Continuous stall torque, max, at max winding temperature in a 40C ambient:	308 Nm (2726 lb-in)
6. Winding temperature, max, in a 40C ambient:	150 degrees C
7. Continuous stall current, max:	50.9 Amps 0 to peak
8. Heatsink size, aluminum, attached to front mounting flange for continuous torque specifications:	508 x 508 x 19.1mm (20 x 20 x 0.75 inch)
9. Peak stall torque, max:	690 Nm (6107 lb-in)
10. Peak stall current, max:	175 Amps 0 to peak
11. Rated Speed (UL file and motor nameplate Rated RPM):	600 RPM
12. Continuous power rating, max:	7.29 kW (9.78 hp)
13. Speed at continuous power rating:	350 RPM
14. Continuous torque, max, at continuous power rating:	199 Nm (1761 lb-in)
15. Continuous current, Ref, at continuous power rating:	32.8 Amps 0 to peak
16. Operating voltage, Ref (Not for direct connection to AC line):	480 VAC RMS
17. Insulation class:	155C (Class F)
18. Housing temperature, max:	125C (257F)
19. Ke, +/-10%, phase to phase at 25C +/- 5C:	820 V/kRPM 0 to peak
20. Kt (sine), Ref, at 25C +/- 5C:	6.78 Nm/Amp (60.01 lb-in/Amp) 0 to peak
21. Winding resistance, +/- 10%, phase to phase at 25C +/- 5C:	0.202 ohms
22. Winding inductance, Ref, phase to phase:	3.82 mH
23. Dielectric rating of motor power connections (U,V,W), to ground for 1 second:	2352 VAC RMS 50/60 Hz
24. Audible noise, Ref, at 1 meter distance:	70 dbA
25. Rotor inertia, +/- 10%:	0.225 kg-m ² (1.99 lb-in-sec ²)
26. Friction torque, Ref:	4.3 Nm (38.1 lb-in)
27. Cogging torque, Ref:	3.08 Nm (27.3 lb-in) peak to peak
28. Thermal resistance, Ref, winding to ambient:	0.152 degrees C/watt
29. Thermal time constant, Ref, winding to ambient:	126 minutes
30. Product weight, Ref:	108 kg (238 lb)
31. Shipping weight, Ref:	116 kg (256 lb)
32. Operating ambient temperature:	0C to 40C (32F to 104F)
33. Storage ambient temperature:	-30C to 70C (-22F to 158F)

Notes:

- "Ref" denotes untoleranced specifications, provided for reference only.
- Speed, torque and current specifications are for operation with Allen Bradley drives.

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	Dr.	S. Johnson	Date	10-13-09	A	00

General Specifications, continued:

- 34. Relative humidity, non-condensing: 5% to 95%
- 35. Liquid / dust protection: IP65
- 36. Shock, max, 6 msec duration: 20 g peak
- 37. Vibration, max, 30 to 2000 Hz: 2.5 g peak
- 38. Bearing arrangement: None internal to motor. Shaft is supported by customer's shaft / bearing system.
- 39. Shaft material: Steel
- 40. Paint color, gloss level, except rear cover: Black, 20 to 35 gloss units
- 41. Rear cover color (Pantone color code), painted or exposed material color: Cool gray # 5, 0 to 20 gloss units
- 42. Shaft, key (if provided), front mounting surface, and connectors are not painted.

Feedback Specifications:

- 1. Feedback interface type (encoder supplier proprietary), order designation: Endat, 2.2/01
- 2. SIN, COS waveform output signals/rev: 2048 sinusoids/rev
- 3. SIN, COS waveform amplitude, measured differentially from SIN+ to SIN-, or COS+ to COS-: 0.75 to 1.2 VAC peak to peak
- 4. SIN, COS voltage offset with respect to ECOM, +/- 0.5 VDC: 2.5 VDC
- 5. DATA+, DATA-, CLK+, CLK- signals applicable standard, signals type: RS 485, Synchronous
- 6. CLK+, CLK- clock frequency, Ref, when operating with Kinetix Endat adapter kit: 468.75 kHz
- 7. Communication hierarchy: Encoder is slave, communication is externally initiated.
- 8. Single turn absolute position value range: 0 to 8191 (13 bit)
- 9. Absolute position data: Binary, value increases with CW shaft rotation viewing motor mounting face.
- 10. Memory storage capacity available for Rockwell parameters, EEPROM, min: 64 words, 16 bits/word
- 11. EPWR 5V (encoder power) input voltage: 3.6 to 14 VDC
- 12. EPWR 5V continuous input current,max, at 5.0 VDC: TBD mADC
- 13. EPWR 5V inrush input current, max, when connected to Kinetix6000 drive: TBD ADC
- 14. TS+, TS- PTC Thermistor transition temperature, +/-5C: 160 degrees C
- 15. TS+, TS- PTC thermistor circuit resistance, Ref, at thermistor transition temperature: 1100 ohms
- 16. TS+, TS- PTC thermistor circuit resistance, Ref, at 25 C +/- 5C: 160 ohms
- 17. TS+, TS- PTC thermistor resistance vs temperature curves applicable standards: DIN 44081 / 44082
- 18. TS+, TS- PTC thermistor circuit configuration (number of thermistors): 2 in series

Notes:

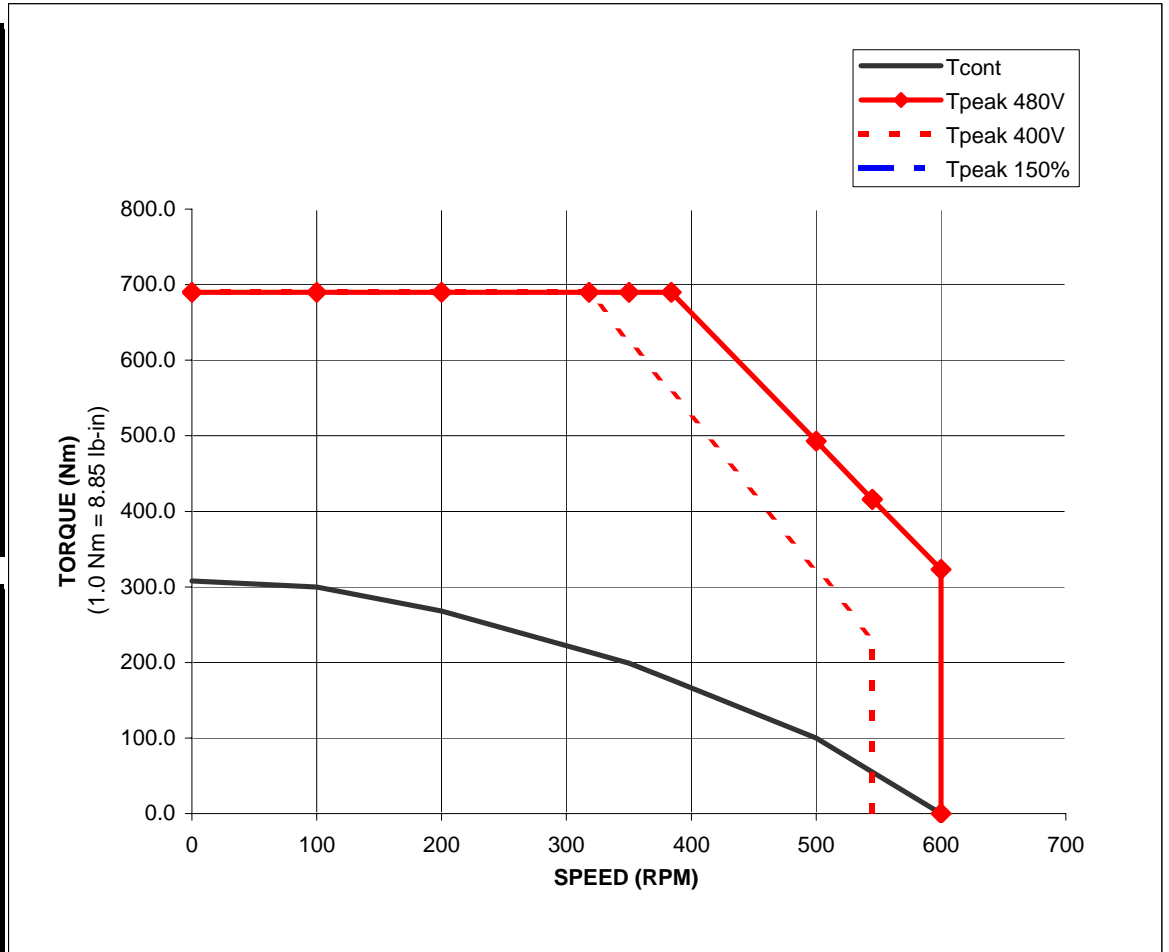
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**RDB-B41026-3B72AA Performance with 2099-BM09S
at 480 and 400 VAC 3 phase Drive Input, 40C Motor Ambient**

SPEED RPM	TORQUE			
	Tcont	Tpeak 480V	Tpeak 400V	Tpeak 150%
	Nm	Nm	Nm	Nm
0	308	690	690	#N/A
100	300	690	690	#N/A
200	268	690	690	#N/A
318	214	690	690	#N/A
350	199	690	625	#N/A
384	177	690	557	#N/A
500	100	493	323	#N/A
545	55	416	232	#N/A
545	55	416	0	#N/A
600	0	323	#N/A	#N/A
600	#N/A	0	#N/A	#N/A
#N/A	#N/A	#N/A	#N/A	#N/A

SPEED RPM	TORQUE			
	Tcont	Tpeak 480V	Tpeak 400V	Tpeak 150%
	lb-in	lb-in	lb-in	lb-in
0	2726	6107	6107	#N/A
100	2655	6107	6107	#N/A
200	2372	6107	6107	#N/A
318	1894	6107	6107	#N/A
350	1761	6107	5532	#N/A
384	1567	6107	4930	#N/A
500	885	4275	2859	#N/A
545	487	3682	2053	#N/A
545	487	3682	0	#N/A
600	0	2859	#N/A	#N/A
600	#N/A	0	#N/A	#N/A
#N/A	#N/A	#N/A	#N/A	#N/A



Notes:

1. Nm torque values shown are converted from tested lb-in data.
2. "Tpeak 150%" line shown applies when the drive peak current limit is set to 150% of the drive continuous current rating.



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Engineering Specification Electrical

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Dr. S. Johnson Date 10-13-09

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