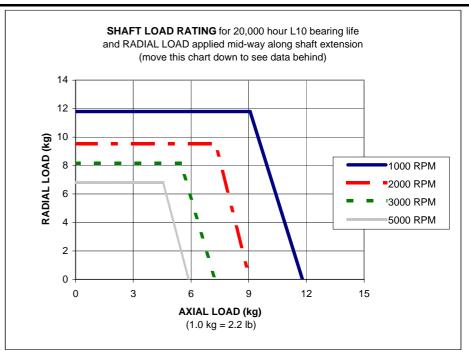
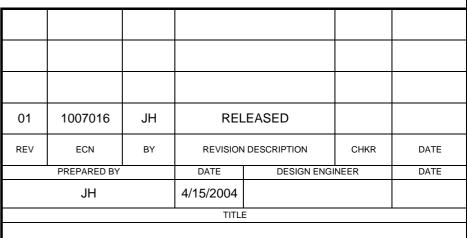


MOTOR MOUNTING FACE





TL-A120P-BJ34AA, ESE

A SIZE

Allen-Bradley

PART NO.

TLA120PBJ34AAESE

SHEET

1 OF

Notes: Print or enlarge waveforms for improved clarity.

For additional specifications see TLA120PBJ34AAESM.

Specifications:

- Motor type: 8 pole, 3 phase, wye winding, permanent magnet rotor, totally enclosed, non-ventilated.
- 2. Operating speed: 5000 RPM max.
- 3. Continuous stall torque: 0.163 Nm (1.44 lb-in) max at 125C winding temperature in a 40C ambient, when mounted on an 8 inch sq x 1/4 inch thick aluminum heatsink.
- 4. Peak stall torque: 0.36 Nm (3.20 lb-in) max.
- 5. Continuous output rating: 0.077 kW (0.103 hp) max at continuous rated operating point: 5000 RPM, 0.147 Nm (1.30 lb-in), 0.93 Amps 0 to peak max.
- 6. Operating voltage: 230 VAC RMS Ref. (Not for direct connection to AC line).
- 7. Continuous stall current: 0.93 Amps 0 to peak max.
- 8. Peak stall current: 2.50 Amps 0 to peak max.
- 9. Insulation class: 155C (Class F).
- 10. Housing temperature: 110C (230F) max.
- 11. Ke: 22.5 to 27.5 (25 nom) V/kRPM 0 to peak, phase to phase at 20C to 30C.
- 12. Kt: (sine) 0.206 Nm/Amp 0 to peak (1.83 lb-in/Amp 0 to peak) Ref at 20C to 30C.
- 13. Winding resistance: 28.8 to 35.2 Ohms, phase to phase at 20C to 30C.
- 14. Winding inductance: 36 mH, phase to phase Ref.
- 15. Dielectric rating of motor power connections (U,V,W) to ground: 1800 VAC RMS 50/60 Hz for 1 second.
- 16. Rotor inertia: 0.000005 kg-m² (0.000044 lb-in-sec²) Ref.
- 17. Rotor balancing: Quality grade G-6.3.
- 18. Friction torque: 0.0025 Nm (0.022 lb-in) Ref.
- 19. Friction torque with shaft seal option installed: 0.0056 Nm (0.050 lb-in) Ref.
- 20. Cogging torque: 0.0021 Nm (0.019 lb-in) peak to peak Ref.
- 21. Damping: 0.0024 Nm/kRPM (0.021 lb-in/kRPM) Ref.
- 22. Thermal resistance, winding to ambient: 1.8 degrees C/watt Ref.
- 23. Thermal time constant, winding to ambient: 5.1 minutes Ref.
- 24. Product weight: 0.59 kg (1.3 lb) Ref.
- 25. Shipping weight: 0.86 kg (1.9 lb) Ref.
- 26. Operating ambient temperature: 0C to 40C (32F to 104F).
- 27. Storage ambient temperature: -10C to 85C (14F to 185F).
- 28. Relative humidity: 20% to 85% non-condensing.
- 29. Liquid / dust protection: IP65 when optional shaft seal is installed, excluding flying lead connectors (connectors rating: IP30).
- 30. Shock: 20 g peak max, 6 msec duration (18 occurances tested).
- 31. Vibration: 2.5 g peak max, 30 to 2000 Hz.
- 32. Bearing arrangement: Outer diameter of rear bearing is trapped axially.
- 33. Shaft material: Steel, grade S45C.

Notes: "Ref" denotes untoleranced specifications, provided for reference only.

Speed, torque and current specifications are for motor operation with Allen Bradley drives.

Brake Specifications:

- 1. Type: Spring-set holding brake, releases when voltage applied.
- 2. Holding torque: 0.32 Nm (2.8 lb-in) max.
- 3. Voltage input: 21.6 to 26.4 VDC, may be applied either polarity.
- 4. Current input: 0.18 to 0.22 ADC at 24 VDC, at 20C to 30C.
- 5. Coil resistance: 103 to 127 Ohms at 20C to 30C.
- 6. Coil resistance: 135 to 165 Ohms with motor operating at max continuous stall torque rating in a 40C ambient.
- 7. Release time delay (when voltage applied): 21 msec Ref.
- Engage time delay (when voltage removed): 40 msec Ref with diode (or 7.0 msec Ref with MOV) used as arc suppression device in external control circuit.
- 9. Rotational backlash: 1.0 degrees Ref with brake engaged.
- 10. Dielectric rating of brake connections (BR+,BR-) to ground: 1200 VAC RMS 50/60 Hz for 1 second.

01		TITLE					
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REV	TL-A120P-BJ34AA, ESE						
Allen-Bradley		PART NO.					
		TLA120PBJ34AAESE					
		A SIZE	SHEET	2	OF	4	

Feedback Specifications:

Encoder Function:

- 1. 17 bit single turn absolute position data is provided, via serial output, with or without an external battery connected.
- 2. 16 bit multi-turn absolute position data is provided, along with the 17 bit single turn absolute position data, via serial output, when an external battery is connected.

Electrical Hardware:

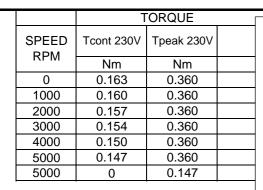
- 1. SD+, SD- (serial data) output / input: RS 485 differential line driver / receiver.
- 2. EPWR (encoder power) voltage input: 4.75 to 5.25 VDC.
- 3. EPWR current input: 60 mADC nominal, 110 mADC max continuous. 1.3 ADC max inrush.
- 4. BAT+ (battery) voltage input: 3.6 VDC nominal.
- 5. BAT+ current input, with +5VDC applied to EPWR input: 3.6 uA nominal.
- 6. BAT+ current input, with no EPWR input applied: 110 uA max.
- 7. Battery alarm fault (battery change required) voltage level: 3.1 VDC Ref.
- 8. Battery error fault (absolute multi-turn position not saved at power loss) voltage level: 2.5 VDC Ref.

Serial Communication:

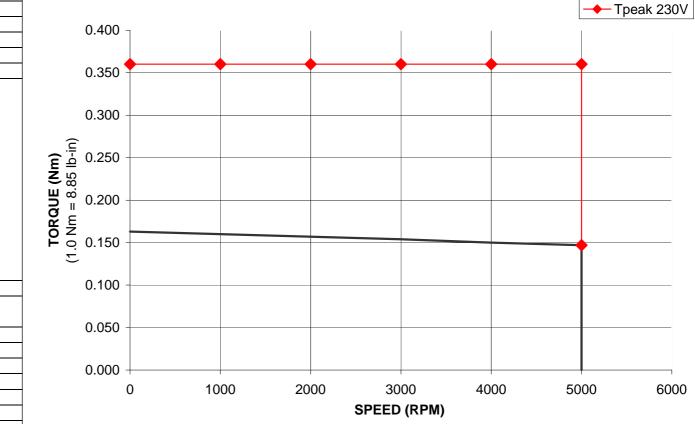
- 1. SD+, SD- serial data rate: 2.5 Mbps, asynchronous.
- 2. Communication hierarchy: Encoder is slave, communication is externally initiated.
- 3. Single turn absolute position value range: 0 to 131,071 (17 bit).
- 4. Multi-turn absolute shaft revolution value range: 0 to 65,535 revolutions (16 bit).
- 5. Absolute position data: Binary, value increases with CCW shaft rotation viewing motor mounting face.
- 6. Memory storage capacity: 80 bytes, EEPROM.

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Note: "Ref" denotes untoleranced specifications, provided for reference only.



TL-A120P-BJ34AA (Ke=25)	Performance with 2092-DA1			
at 230 VAC Drive Input, 40C Motor Ambient				



	TORQUE			
SPEED RPM	Tcont 230V	Tpeak 230V		
	lb-in	lb-in		
0	1.44	3.20		
1000	1.42	3.20		
2000	1.39	3.20		
3000	1.36	3.20		
4000	1.33	3.20		
5000	1.30	3.20		

Note: Nm torque values shown are converted from tested lb-in data.

O1

REV

TL-A120P-BJ34AA, ESE

PART NO.

Tcont 230V

Allen-Bradley TLA120PBJ34AAESE

A SIZE SHEET 4 OF