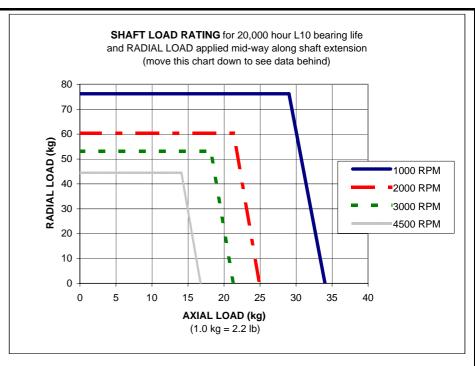
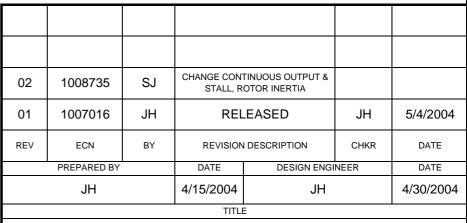


MOTOR MOUNTING FACE





TL-A410M-BJ34AA, ESE

A SIZE

Allen-Bradley

PART NO.

TLA410MBJ34AAESE

SHEET

1 of

Notes: Print or enlarge waveforms for improved clarity.

For additional specifications see TLA410MBJ34AAESM.

Specifications:

- Motor type: 8 pole, 3 phase, wye winding, permanent magnet rotor, totally enclosed, non-ventilated.
- 2. Operating speed: 4500 RPM max.
- 3. Continuous stall torque: 4.86 Nm (43 lb-in) max at 155C winding temperature in a 40C ambient, when mounted on a 12 inch sq x 1/2 inch thick aluminum heatsink.
- 4. Peak stall torque: 13 Nm (115 lb-in) max.
- 5. Continuous output rating: 1.8 kW (2.4 hp) max at continuous rated operating point: 4500 RPM, 3.84 Nm (34 lb-in), 11.7 Amps 0 to peak max.
- 6. Operating voltage: 230 VAC RMS Ref. (Not for direct connection to AC line).
- 7. Continuous stall current: 14.0 Amps 0 to peak max.
- 8. Peak stall current: 43.4 Amps 0 to peak max.
- 9. Insulation class: 155C (Class F).
- 10. Housing temperature: 125C (257F) max.
- 11. Ke: 42.3 to 51.7 (47 nom) V/kRPM 0 to peak, phase to phase at 20C to 30C.
- 12. Kt: (sine) 0.388 Nm/Amp 0 to peak (3.44 lb-in/Amp 0 to peak) Ref at 20C to 30C.
- 13. Winding resistance: 0.711 to 0.869 Ohms, phase to phase at 20C to 30C.
- 14. Winding inductance: 3.1 mH, phase to phase Ref.
- 15. Dielectric rating of motor power connections (U,V,W) to ground: 1800 VAC RMS 50/60 Hz for 1 second.
- 16. Rotor inertia: 0.00041 kg-m² (0.0036 lb-in-sec²) Ref.
- 17. Rotor balancing: Quality grade G-6.3.
- 18. Friction torque: 0.051 Nm (0.45 lb-in) Ref.
- 19. Friction torque with shaft seal option installed: 0.080 Nm (0.71 lb-in) Ref.
- 20. Cogging torque: 0.080 Nm (0.71 lb-in) peak to peak Ref.
- 21. Damping: 0.020 Nm/kRPM (0.18 lb-in/kRPM) Ref.
- 22. Thermal resistance, winding to ambient: 0.37 degrees C/watt Ref.
- 23. Thermal time constant, winding to ambient: 21 minutes Ref.
- 24. Product weight: 6.8 kg (15 lb) Ref.
- 25. Shipping weight: 7.7 kg (17 lb) Ref.
- 26. Operating ambient temperature: 0C to 40C (32F to 104F).
- 27. Storage ambient temperature: -10C to 85C (14F to 185F).
- 28. Relative humidity: 20% to 85% non-condensing.
- 29. Liquid / dust protection: IP65 when optional shaft seal is installed, excluding flying lead connectors (connectors rating: IP30).
- 30. Shock: 20 g peak max, 6 msec duration (18 occurances tested).
- 31. Vibration: 2.5 g peak max, 30 to 2000 Hz.
- 32. Bearing arrangement: Outer diameter of rear bearing is trapped axially.
- 33. Shaft material: Steel, grade S45C.

Notes: "Ref" denotes untoleranced specifications, provided for reference only.

Speed, torque and current specifications are for motor operation with Allen Bradley drives.

34. Paint: Black. Shaft, key (if provided), front mounting surface, and flying lead cables are not painted.

Brake Specifications:

- 1. Type: Spring-set holding brake, releases when voltage applied.
- 2. Holding torque: 9.3 Nm (82 lb-in) max.
- 3. Voltage input: 21.6 to 26.4 VDC, may be applied either polarity.
- 4. Current input: 0.648 to 0.792 ADC at 24 VDC, at 20C to 30C.
- 5. Coil resistance: 29.7 to 36.3 Ohms at 20C to 30C.
- 6. Coil resistance: 40.5 to 49.5 Ohms with motor operating at max continuous stall torque rating in a 40C ambient.
- 7. Release time delay (when voltage applied): 69 msec Ref.
- Engage time delay (when voltage removed): 84 msec Ref with diode (or 20 msec Ref with MOV) used as arc suppression device in external control circuit.
- 9. Rotational backlash: 1.0 degrees Ref with brake engaged.
- 10. Dielectric rating of brake connections (BR+,BR-) to ground: 1200 VAC RMS 50/60 Hz for 1 second.

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REV	TL-A410M-BJ34AA, ESE							
Allen-Bradley		PART NO.						
		TLA410MBJ34AAESE						
		A SIZE	SHEET	2	OF	4		

Feedback Specifications:

Encoder Function:

- 1. 17 bit single turn absolute position data is provided, via serial output, with or without an external battery connected.
- 2. 16 bit multi-turn absolute position data is provided, along with the 17 bit single turn absolute position data, via serial output, when an external battery is connected.

Electrical Hardware:

- 1. SD+, SD- (serial data) output / input: RS 485 differential line driver / receiver.
- 2. EPWR (encoder power) voltage input: 4.75 to 5.25 VDC.
- 3. EPWR current input: 60 mADC nominal, 110 mADC max continuous. 1.3 ADC max inrush.
- 4. BAT+ (battery) voltage input: 3.6 VDC nominal.
- 5. BAT+ current input, with +5VDC applied to EPWR input: 3.6 uA nominal.
- 6. BAT+ current input, with no EPWR input applied: 110 uA max.
- 7. Battery alarm fault (battery change required) voltage level: 3.1 VDC Ref.
- 8. Battery error fault (absolute multi-turn position not saved at power loss) voltage level: 2.5 VDC Ref.

Serial Communication:

- 1. SD+, SD- serial data rate: 2.5 Mbps, asynchronous.
- 2. Communication hierarchy: Encoder is slave, communication is externally initiated.
- 3. Single turn absolute position value range: 0 to 131,071 (17 bit).
- 4. Multi-turn absolute shaft revolution value range: 0 to 65,535 revolutions (16 bit).
- 5. Absolute position data: Binary, value increases with CCW shaft rotation viewing motor mounting face.
- 6. Memory storage capacity: 80 bytes, EEPROM.

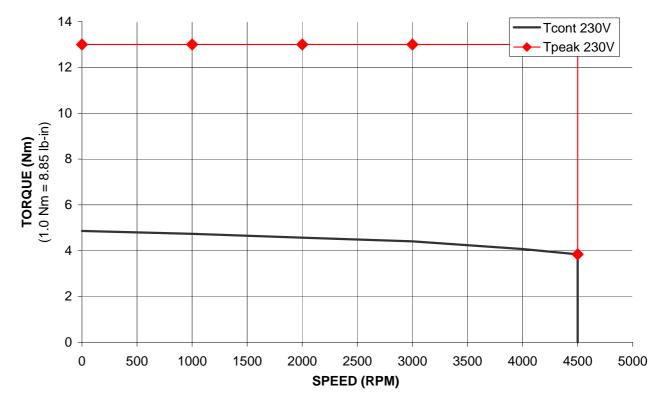
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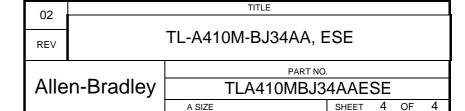
Note: "Ref" denotes untoleranced specifications, provided for reference only.

TORQUE			
SPEED RPM	Tcont 230V	Tpeak 230V	
KFIVI	Nm	Nm	
0	4.86	13	
1000	4.74	13	
2000	4.57	13	
3000	4.41	13	
4000	4.07	13	
4500	3.84	13	
4500	0	3.84	

	TORQUE			
SPEED RPM	Tcont 230V	Tpeak 230V		
KEIVI	lb-in	lb-in		
0	43	115		
1000	42	115		
2000	40.5	115		
3000	39	115		
4000	36	115		
4500	34	115		

TL-A410M-BJ34AA (Ke=47) Performance with 2092-DA5 at 230 VAC 3 phase Drive Input, 40C Motor Ambient





Note: Nm torque values shown are converted from tested lb-in data.